

## Real-Time Specification for Java and certification aspects.

... Profitting from Java in embedded, realtime and safety-critical applications.



Dr.-Ing. Fridtjof Siebert Director of Development, aicas GmbH Java Forum Stuttgart, 3. July 2003



## aicas GmbH — Company Profile

## Who is aicas GmbH?

**Aim:** Promotion of modern software development methods in embedded and time-critical control, systems.

aicas's partners and customers:





















csem













## aicas GmbH — Company Profile

## aicas Java activities

**European projects:** 

**HIDOORS** High Integrity Distributed Object-

Oriented Realtime Systems

**ESA** activities:

**AERO** Architecture for Enhanced

Reprogrammability...

RT Java Standardisation:

**J-Consortium** active member, work on RTDA

The Open Group RT Java group

Java User Community:

**JUGS, JUG** Java User Groups

Live Embedded-Linux Group



## Java Technology for Realtime Systems

## Deeply embedded realtime applications











## **Examples:**

automotive, avionic, industrial automation, telecom, medical, ...



## Why Java Technology for realtime systems?

- Higher productivity
- Platform independence
- Reliability (type/pointer safety)
- Flexibility (dynamic loading)

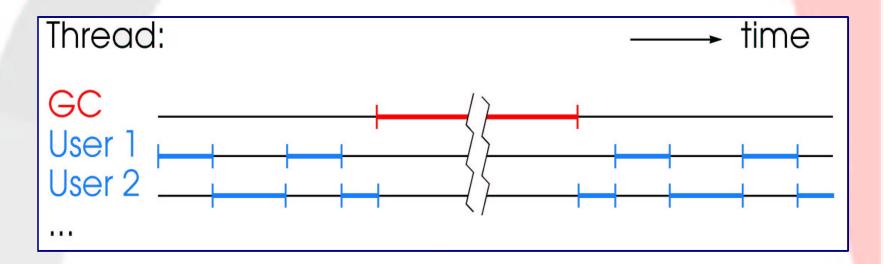
#### **Problems:**

- Memory requirements
- Poor runtime performance
- Lack of realtime guarantees



## Classic Garbage Collector

GC can stop execution for long periods of time:



#### **Problem:**

long, unpredictable pauses during execution.



#### Realtime Specification for Java: Overview

## Real-Time Specification for Java (RTSJ)

Extension of Java APIs to allow realtime programming

### Areas addressed by the RTSJ:

- Thread Scheduling
- Synchronisation
- Memory Management
- Asynchronous Events
- Asynchronous Control Flow / Thread Termination
- Access to physical memory



## Threads in the RTSJ

Realtime-Threads with at least 28 new priority levels:

#### **New thread classes:**

- RealtimeThread
- NoHeapRealtimeThread

Priority preemptive scheduling for these threads.

Priorities are higher than those of standard Java threads.

## Realtime Specification for Java: Overview

## **Synchronisation**

Priority Inversion Avoidance mechanisms:

### **Priority Inheritance Protocol:**

Default behaviour of Java Monitors

## **Priority Ceiling Protocol:**

Optional protocol



## **Memory Management**

#### Aims:

- predictable allocation
- no garbage collection in critical code

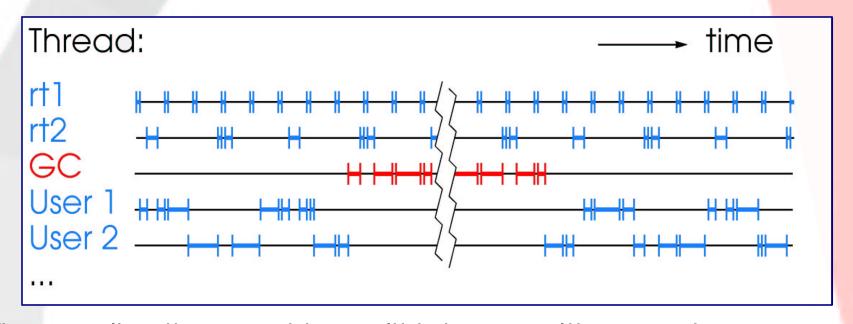
#### New memory areas are available:

- ImmortalMemory -- never collected
- ScopedMemory -- stack-like allocation



## Garbage Collection in the RTSJ

Only special threads can interrupt the garbage collector::



The application must be split into a realtime and a non-realtime part. Synchronization between these parts is not possible!



## **Asynchronous Events**

Implementation of Interrupt Handlers.

#### **Features:**

- Similar to Realtime Threads
- Priority and scheduling parameters such as Threads
- Handlers are executed in a thread context
- This context might change between invocations

#### Realtime Specification for Java: Overview

## **Asynchronous Control Flow**

Mechanism to throw an exception into another thread.

### **Applications:**

- Provide a time-out for a calculation
- Terminate a thread that is no longer used



## **Access to Physical Memory**

Safe access to physical memory regions:

### **Examples:**

- Memory Mapped IO
- On-chip caches

## Two Ways to access phyiscal memory:

- Raw-Memory, i.e., byte-wise
- As an Memory Area to store Java objects

#### Realtime Specification for Java: Overview

## Periodic Thread Example

```
/* priority for new thread: min+10 */
int pri = PriorityScheduler.instance().getMinPriority()+10;
PriorityParameters prip = new PriorityParameters(pri);
RelativeTime period = new RelativeTime(20 /* ms */,0 /* ns */);
/* release parameters for periodic thread: */
PeriodicParameters perp = new PeriodicParameters(null,period,null,null,null,null);
/* create periodic thread: */
RealtimeThread rt= new RealtimeThread(prip,perp) {
 public void run() {
  int n=1:
  while (waitForNextPeriod() && (n<100)) {
   System.out.println("Hello "+n);
   n++;
rt.start();
```



## Garbage Collection in the RTSJ

The RTSJ permit the development of realtime applications, but

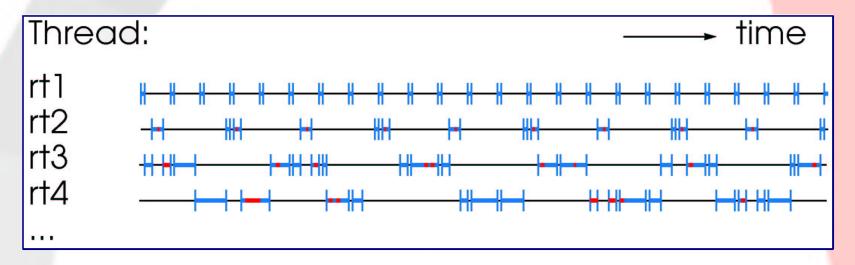
- realtime code must be separated from 'normal' code
- realtime code can use only special memory areas
- No Garbage Collection, danger of memory leaks
- Danger of Priority-Inversion when synchronization with non-realtime-code

Realtime code can use only a subset of Java features!



## Realtime Garbage Collection

All Java-Threads must be realtime threads:



- GC-work is performed at allocation time
- GC-work must be sufficient to recycle enough memory before free memory is exhausted
- WCET for memory allocation is required

amaicaVM



## Relaxing Constraints of RTSJ with Realtime Garbage Collection

The use of realtime garbage collection permits all threads to access the garbage collected heap.

- No restriction of heap access in realtime code
- Synchronization between realtime and non-realtime code directly possible

JamaicaVM provides realtime garbage collection.

It was used as the basis for the development in the AERO project.



## AERO-JVM Java Implementation for Satellite Onboard Software

Developed by a consortium of

- Astrium SAS, France
- aicas GmbH, Germany
- University of Linköping, Sweden
- ESA ESTEC, Netherlends

Work based on JamaicaVM.

Preparation for certification of VM in space domain part of the project.



## **AERO-JVM**, Java Technology for Onboard SW

# Tasks Performed within the AERO project:

#### **Evaluation of available Java solutions**

Selection of JamaicaVM as basis

## Specification of needs for space system

### **Implementation**

- RTSJ support
- testsuite
- Port for ERC32 and Leon target system
- Static GC

#### **Validation**



#### **AERO-JVM Validation and Certification**

## Validation with Space Applications

## **OBJA Manager**

Java-Version of state-of-the-art interpreted procedure used on Rosetta and E3000 family of telecom satellites.

Consists of mode manager, monitoring, reprogrammable mission functions etc.

Attitude Control System algorithms

**Orbit propagator** 





## **C-Code Coverage**

## **Determined using toolg gcov**

raw value: 61.80%

Adjusted value: 84.73%

#### Acceptable for beta product

Detailed description of all C-routines, that are not covered or covered only partially



#### **AERO-JVM Validation and Certification**

## **C-Code Coverage**

#### routine

allocJavaString allocAndInternJavaString catJavaString utf82javaString c2javaString class2javaString feature2javaString feat2javaString

## covrg. explanation

partial - count argument is always -1 (design)
partial - Error checking code (Java exception)
partial - Error checking code (out of memory)
partial - utf8 argument is never null (design)
partial - cstr argument is never null (design)
complete
none - Error checking code

partial facture groupent is no

partial - feature argument is never null (design)

#### etc.



## **AERO-JVM Validation and Certification**

## **Test Suite Results**

<b>Testsuite</b>	pass	fail
AERO tests	1506	0
Jamaica Tests	50309	2
MAUVE tests	5558	79





## **AERO Project Traceability**

### **Specification defines Requirements**

unique id: e.g. REQ/ AERO. RT. SCH. 0020

evaluation method: test / analysis / code inspection

#### Validation Plan

Describes tests to developed

## **Design Document**

Describes mapping of requirements to source code

#### **Evaluation Document**

Validation results



## **AERO Project Future**

## First Phase Finished Successfully Second Phase of the Project is being set up

Goals of second phase

- Further Validation towards certifiability:
  - 100% code coverage
  - Removal of dead code
  - Extension of tests to cover open cases
- First Mission: Proba 2 (launch scheduled for 2005)



## **Conclusions**

The RTSJ specification brings features required for realtime programming in the Java language.

The combination with realtime garbage collection overcomes the restrictions of the RTSJ.

Java Implementations that will be certified for use in safety critical applications are being developed and will be the next step.

More information:

www.aicas.com

www.aero-project.org